

DYNAMICS IN GROUPS

V .V. S. Ramachandram

Associate Professor, B.V.C. College of Engineering,
Rajahmundry, Andhra Pradesh, India.

Abstract

In this paper we defined a dynamical system (G, f) where G is a group and ' f ' is a homomorphism from G to itself. We established some properties of the set of fixed points and the set of periodic points. We proved that the set of all fixed points is a subgroup of G and it is a strongly invariant subset of G .

Introduction

Discrete dynamical system is an exciting and very active field in pure and applied mathematics that involves tools and techniques from many areas such as analysis, geometry and number theory. In the present paper on dynamics in groups, we established some properties of the set of fixed points and the set of periodic points.

Key words: Discrete dynamical system, Homomorphism, Periodic point, Fixed point, Strongly invariant set.

Mathematic Subject Classification: 55F08, 58F11, 54H20, 28D05

Basic Definitions

Discrete dynamical system: Let G be a group and $f : G \rightarrow G$ be a homomorphism. Then (G, f) is a discrete dynamical system.

In the present paper whenever we say "a dynamical system" it means we are taking an ordered pair (G, f) where G is a group and $f : G \rightarrow G$ is a homomorphism.

Fixed point: In the dynamical system (G, f) a point $a \in G$ is a fixed point if $f(a) = a$.

Periodic point: In the dynamical system (G, f) a point $a \in G$ is a periodic point if $f^n(a) = a$ for some positive integer n . The least value of n is called the period of ' a '.

Invariant set: In the dynamical system (G, f) a subset A of G is invariant if $f(A) \subset A$.

Ex. (2): In the above group, the subset $A = \{-i, i\}$ is a strongly invariant subset of G .

Main Theorems

Theorem 1: In the dynamical system (G, f) the set of all fixed points in G is a subgroup of G .

Proof: Let H be the set of all fixed points and 'e' be the identity in G .

Since 'e' is a fixed point, so $H \neq \emptyset$.

Let $a, b \in H \Rightarrow f(a) = a$ and $f(b) = b$.

By homomorphism property and $f(a^{-1}) = (f(a))^{-1}$, we have

$$f(aob^{-1}) = f(a)of(b^{-1}) = f(a)o(f(b))^{-1} = aob^{-1}.$$

This shows that $aob^{-1} \in H$. This completes the proof.

Theorem 2: In the dynamical system (G, f) the set of all periodic points in G is a subgroup of G .

Proof: Let K be the set of all periodic points in the group G .

Since 'e' is a periodic point, K is a nonempty subset of G .

Let $a, b \in K$ and their periods be m and n respectively. Put $r = \text{L.C.M of } \{m, n\}$.

By Result (4) and $f^r(a^{-1}) = [f^r(a)]^{-1} = a^{-1}$ we can get,

$$f^r(aob^{-1}) = f^r(a)of^r(b^{-1}) = f^r(a)o(f^r(b))^{-1} = aob^{-1}$$

This shows that $aob^{-1} \in K$. This completes the proof.

Theorem 3: In the dynamical system (G, f) the set of all fixed points in G is s-invariant.

Proof: Let A be the set of all fixed points in G .

$$\text{Let } f(a) \in f(A) \Rightarrow a \in A \Rightarrow f(a) = a \Rightarrow f(a) \in A$$

Now, $a \in A \Rightarrow f(a) \in f(A) \Rightarrow a \in f(A)$ which shows that $f(A) = A$.

Theorem 4: In the dynamical system (G, f) if 'a' is a fixed point and 'b' is a periodic point in G then 'aob' is a periodic point in G .

Proof: Since 'a' is a fixed point $f(a) = a$.

Let the period of the point 'b' be k so that $f^k(b) = b$.

$$f^2(a) = f(f(a)) = f(a) = a \quad \text{and} \quad f^k(a) = f(f^{k-1}(a)) = f(a) = a$$

Therefore by the homomorphism property of f^k and the above equality, we get

$$f^k(aob) = f^k(a)of^k(b) = aob, \text{ which shows that 'aob' is periodic.}$$

Theorem 5: In the dynamical system (G, f) if A is a subset of G such that $f(G) \subset A \subset G$, then A is invariant with respect to f .

Proof: $A \subset G \Rightarrow f(A) \subset f(G) \Rightarrow f(A) \subset A$. Hence, A is an invariant set in G .

Theorem 6: If G is an abelian group and $f : G \rightarrow G$ is defined by $f(a) = a^{-1}$, then in the dynamical system (G, f) every point except the identity is a periodic point of period 2.

Proof: Let $a \neq e$ be a point in G .

$$\text{Then } f^2(a) = f(f(a)) = f(a^{-1}) = (a^{-1})^{-1} = a, \text{ which shows that } a \text{ is of period 2.}$$

Note: In the above theorem if G is not commutative then the function f need not be a homomorphism.

Conclusion: In the present paper, we proved that the set of all periodic points in the dynamical system (G, f) is a subgroup of G . We have given an example to show that there are some dynamical systems in which except some points all other points have period 2.

Acknowledgements:

I am very much thankful to my guide Dr.B. Sankara Rao, Adikavi Nannaya University, Rajahmundry for his suggestions in preparing the paper.

References:

- [1] R. L. Devaney, "*Chaotic Dynamical systems*" (second edition), Addison-Wesley, 1989.
- [2] M.Brin & G.Stuck, "*Introduction to Dynamical systems*", Cambridge University Press.
- [3] I.N.Herstein, "*Topics in Algebra*", Willey India (P) Ltd, 2nd edition, 2006.
- [4] Kim, K. H., Roush, F.W., *Linear Algebra and Its Applications*, 379-457, 2004.
- [5] Ledermann, Walter, "*Introduction to the theory of finite groups*", Oliver and Boyd, Edinburgh and London, 1953.
- [6] Ledermann, Walter, "*Introduction to group theory*", New York: Barnes and Noble, 1973.

[7] Robinson, Derek John Scott, “*A course in the theory of groups*”, Berlin, New York: Springer-Verlag 1996.

[8] Herstein, Israel Nathan, “*Abstract algebra*” (3rd ed.), Upper Saddle River, NJ: Prentice Hall Inc., 1996.