

ON CERTAIN GAUSS-TYPE QUADRATURE RULES

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ABSTRACT

In this short note we give some comments to recent paper by M.A. Bokhari, A. Qadir, and H. Al-Attas, On Gauss-type quadrature rules. Numer. Funct. Anal. Optime. 31 (2010), 1120-1134. Their polynomials are a special case of the Jacobi polynomials on (0,1). In addition we construct orthogonal polynomials $\pi_n(x)$, $n=0,1,\dots$, and the corresponding Gaussian quadrature rules with respect to the linear B -spline (as a weight function) and give some numerical examples in order to illustrate an application of such quadratures.

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1. Introduction. Recently Bokhari, Qadir, and Al-Attas [1] considered Gauss-type quadrature rules based on polynomials $p_n(t)$ orthogonal on (0,1) with respect to the linear weight function $\omega(t) := 1 - t$. They discussed a development of $p_n(t)$ via Gaussian hypergeometric differential equation, narrated some of its properties, derived the three-term recurrence relation for the monic polynomials

$$p_{n+1}(t) = \left(t - \frac{2(n+1)^2 - 1}{4(n+1)^2 - 1} \right) p_n(t) - \frac{n(n+1)}{4(2n+1)^2} p_{n-1}(t), n = 0, 1, \dots \quad (1.1)$$

where $p_0(t) = 1$ and $p_{-1}(t) = 0$, and considered several numerical examples of such kind of quadratures.

In this short note we show that these polynomials $p_n(t)$ are a special case of the well-known Jacobi polynomials on (0,1). In Section 3 we construct orthogonal polynomials $\pi_n(x)$, $n=0,1,\dots$, and the corresponding Gaussian quadrature rules with respect to the linear B -spline (as a weight function). Finally, in Section 4 we

give some numerical examples to illustrate and application of such quadratures.

2. Jacobi Polynomials on (0,1). Let $w(x) = (1-x)^\alpha (1+x)^\beta$, $\alpha, \beta > -1$, and

$\{\hat{P}_n^{(\alpha, \beta)}(x)\}$ be a sequence of the corresponding monic Jacobi polynomials, which satisfy the three-term recurrence relation (cf. [8, pp. 131-140])

$$\hat{P}_{n+1}^{(\alpha, \beta)}(x) = (x - \hat{\alpha}_n) \hat{P}_n^{(\alpha, \beta)}(x) - \hat{\beta}_n \hat{P}_{n-1}^{(\alpha, \beta)}(x), n = 0, 1, \dots,$$

where $\hat{P}_0^{(\alpha, \beta)}(x) = 1, \hat{P}_{-1}^{(\alpha, \beta)}(x) = 0$, and

$$\hat{\alpha}_n = \frac{\beta^2 - \alpha^2}{(2n + \alpha + \beta)(2n + \alpha + \beta + 2)} \quad (n \geq 0),$$

$$\hat{\beta}_n = \frac{4n(n + \alpha)(n + \beta)(n + \alpha + \beta)}{(2n + \alpha + \beta)^2 [(2n + \alpha + \beta)^2 - 1]} \quad (n \geq 1),$$

except when ; then .

By a change of variables $x = 2t - 1$ we get the monic orthogonal polynomials $p_n^{(\alpha, \beta)}(t) (= 2^{-n} \hat{P}_n^{(\alpha, \beta)}(2t - 1))$ orthogonal on (0,1) with respect to the weight function $\omega(t) := (1-t)^\alpha t^\beta$, $\alpha, \beta > -1$. The coefficients in their three-term recurrence relation

$$p_{n+1}^{(\alpha, \beta)}(t) = (t - \alpha_n) p_n^{(\alpha, \beta)}(t) - \beta_n p_{n-1}^{(\alpha, \beta)}(t), \quad n = 0, 1, \dots, \quad (2.1)$$

are

$$\alpha_n = \frac{1}{2}(1 + \hat{\alpha}_n) = \frac{(2n + \alpha + \beta + 1)^2 - (1 + \alpha^2 - \beta^2)}{2[(2n + \alpha + \beta + 1)^2 - 1]} \quad (n \geq 0),$$

$$\beta_n = \frac{1}{4} \hat{\beta}_n = \frac{n(n + \alpha)(n + \beta)(n + \alpha + \beta)}{(2n + \alpha + \beta)^2 [(2n + \alpha + \beta)^2 - 1]} \quad (n \geq 1).$$

For $\alpha = 1$ and $\beta = 0$, this relation (2.1) gives orthogonal polynomials $p_n(t)$ discussed in [1], which satisfy the relation (1.1).

Now, we list the parameters $\alpha_n (n \geq 0)$ and $\beta_n (n \geq 1)$ for some other special cases:

(a) $\alpha = 0, \beta = 1$.

$$\alpha_n = \frac{2(n+1)^2}{(2n+1)(2n+3)}, \beta_n = \frac{n(n+1)}{4(2n+1)^2};$$

(b) $\alpha = 1, \beta = 1.$

$$\alpha_n = \frac{1}{2}, \beta_n = \frac{n(n+2)}{4(2n+1)(2n+3)};$$

(c) $\alpha = 2, \beta = 0.$

$$\alpha_n = \frac{n^2 + 3n + 1}{2(n+1)(n+2)}, \beta_n = \frac{n^2(n+2)^2}{4(n+1)^2(2n+1)(2n+3)};$$

(d) $\alpha = 2, \beta = 1.$

$$\alpha_n = \frac{2(n+1)(n+3)}{(2n+3)(2n+5)}, \beta_n = \frac{n(n+3)}{4(2n+3)^2};$$

(e) $\alpha = 2, \beta = 2.$

$$\alpha_n = \frac{1}{2}, \beta_n = \frac{n(n+4)}{4(2n+3)(2n+5)};$$

(f) $\alpha = 3, \beta = 0.$

$$\alpha_n = \frac{2n^2 + 8n + 3}{(2n+3)(2n+5)}, \beta_n = \frac{n^2(n+3)^2}{4(n+1)(n+2)(2n+3)^2};$$

(g) $\alpha = 3, \beta = 1.$

$$\alpha_n = \frac{(n+1)(n+4)}{2(n+2)(n+3)}, \beta_n = \frac{n(n+1)(n+3)(n+4)}{4(n+2)^2(2n+3)(2n+5)};$$

(h) $\alpha = \beta = -1/2.$

$$\alpha_n = \frac{1}{2}, \beta_1 = \frac{1}{8}, \beta_n = \frac{1}{16}(n \geq 2), \text{ etc.}$$

Remark 2.1. The relation (2.1) can be obtained taking $w(x) = |x|^\gamma (1-x^2)^\alpha$, with and the corresponding generalized Gegenbauer polynomials, where, which were introduced by Lasčėnov [7] (see, also, [2, pp. 155-156] and [8, pp. 147-148]). Their three-term recurrence relation is

$$W_{n+1}^{(\alpha, \beta)}(x) = xW_n^{(\alpha, \beta)}(x) - B_n W_{n-1}^{(\alpha, \beta)}(x), W_0^{(\alpha, \beta)}(x) = 1, W_{-1}^{(\alpha, \beta)}(x) = 0,$$

with recursion coefficients

$$B_{2n} = \frac{n(n+\alpha)}{(2n+\alpha+\beta)(2n+\alpha+\beta+1)}, B_{2n-1} = \frac{(n+\beta)(n+\alpha+\beta)}{(2n+\alpha+\beta-1)(2n+\alpha+\beta)},$$

except $\alpha + \beta = -1$; then $B_1 = \beta + 1$.

Since the weight function is even on $(-1,1)$, using Theorems 2.2.11 and 2.2.12 from [8, pp. 102-103], we get (2.1) for polynomials orthogonal with respect to the weight $\omega(t) = w(\sqrt{t})/\sqrt{t} = t^\beta(1-t)^\alpha$, with $\alpha_0 = B_1 = (\beta+1)/(\alpha+\beta+2)$, $\alpha_n = B_{2n} + B_{2n+1}$, $\beta_n = B_{2n-1}B_{2n}, n \geq 1$.

3. A Gaussian quadrature formula. Sometimes in applications it could be of some interest to construct orthogonal polynomials $\pi_n(x), n=0,1,\dots$, and the corresponding Gaussian quadrature rules with respect to the linear B -spline (as a weight function)

$$w(x) = B_1(x) = \begin{cases} 1+x, & -1 \leq x \leq 0 \\ 1-x & 0 < x \leq 1 \\ 0, & \text{otherwise,} \end{cases}$$

i.e.,

$$\int_R f(x) B_1(x) dx = \int_{-1}^1 f(x) (1+|x|) dx = \sum_{k=1}^n A_k f(x_k) + R_n(f), \quad (3.1)$$

where $R_n(p) = 0$ for all polynomials p of degree at most $2n-1$.

This weight function is an even extension of $\omega(t) = 1-t$ from $(0,1)$ to $(-1,1)$. The coefficients in the three-term recurrence relation for the corresponding monic orthogonal polynomials $\pi_n(x)$,

$$\pi_{n+1}(x) = x\pi_n(x) - \beta_n\pi_{n-1}(x), n=1,2,\dots$$

are

$$\beta_0 = 1, \beta_1 = 1/6, \beta_2 = 7/30, \beta_3 = 57/245, \beta_4 = 683/2793, \beta_5 = 207725/856482,$$

$$\beta_6 = 286749501/1159331030, \beta_7 = 286268318986/1164429355245,$$

$$\beta_8 = 272609711230510/1097298927604497, \text{ etc.}$$

For example,

$$\pi_0(x) = 1, \pi_1(x) = x, \pi_2(x) = x^2 - \frac{1}{6}, \pi_3(x) = x^3 - \frac{2x}{5}, \pi_4(x) = x^4 - \frac{31x^2}{49} + \frac{19}{490},$$

$$\pi_5(x) = x^5 - \frac{50x^3}{57} + \frac{109x}{798}, \pi_6(x) = x^6 - \frac{16825x^4}{15026} + \frac{2179x^2}{7513} - \frac{5935}{631092}, \text{ etc.}$$

In numerical construction we use our Mathematica Package “Orthogonal Polynomials” [3]. In order to construct quadrature rules up to n points we need the moment $\mu_k = \int_R x^k B_1(x) dx, k=0,1,\dots,2n-1$, which are in our case given by

$$\mu_k = \frac{1+(-1)^k}{(k+1)(k+2)}, k \geq 0.$$

By the mentioned Package, in this case, we can obtain the recursion coefficients, α_k ($=0$ in this symmetric case) and, in a symbolic form for a reasonable n :

`{alpha, beta}=aChebyshevAlgorithm[moments, Algorithm->Symbolic];`

taking, for example, the first 800 moments,

`moments= Table [(1+(-1)^k)/((1+k)(2+k)), {k,0,800}];`

This enables us to construct parameters in Gaussian quadrature

$$Q_n(f) = \sum_{k=1}^n A_k^{(n)} f(x_k^{(n)})$$

up to $n \leq 400$ nodes. For example, for $n=100$, with Precision $\rightarrow 40$, the statement is the following

`{n100,w100}=aGaussianNodesWeights[100,alpha,beta,
WorkingPrecision->50, Precision->40];`

where n100 and w100 are sequences of nodes $x_k^{(n)}, k=1,\dots,n$, and Christoffel numbers $A_k^{(n)}, k=1,\dots,n$, respectively. The last command implements the wellknown Golub-Welsch algorithm [6].

The corresponding software in Matlab was given by Gautschi [4], The first FORTRAN package of routines ORTHPOL was also developed by Walter Gautschi [5] in 1994.

4. Numerical results. In this section we consider three integrals

$$I_k = \int_R f_k(x) B_1(x) dx, k=1,2,3,$$

for the functions $f_1(x) = \cos(\pi x)$,

$$f_2(x) = \frac{1}{\left(x + \frac{3}{10}\right)^2 + \frac{1}{100}} + \frac{1}{\left(x - \frac{9}{10}\right)^2 + \frac{1}{25}} \quad \text{and} \quad f_3(x) = \frac{2}{2 + \sin(10\pi x)},$$

and then apply the quadrature formula (3.1) for their calculation. The first function is smooth, the second is quasi-singular, and the last is an oscillatory function.

The graphics of integrands $f_k(x) B_1(x), k=1,2$, are displayed in Fig. 4.1, and the

graphic of the oscillatory function $f_3(x)B_1(x)$ is presented in Fig. 4.2

Using our Mathematica Package “Orthogonal Polynomials” [5] we constructed n -point Gaussian rules for $n=5; 10(10)50; 100(50)400$. Then, we applied these rules to integrals $I_k, k=1,2,3$, and compared the obtained results with the exact values

$$I_1 = 4 / \pi^2 = 0.405284734569351085775517852838910555617435...$$

$$I_2 = 22.3859074908351131640822746542985712503464...$$

$$I_3 = 1.15470053837925152901829756100391491129520...$$

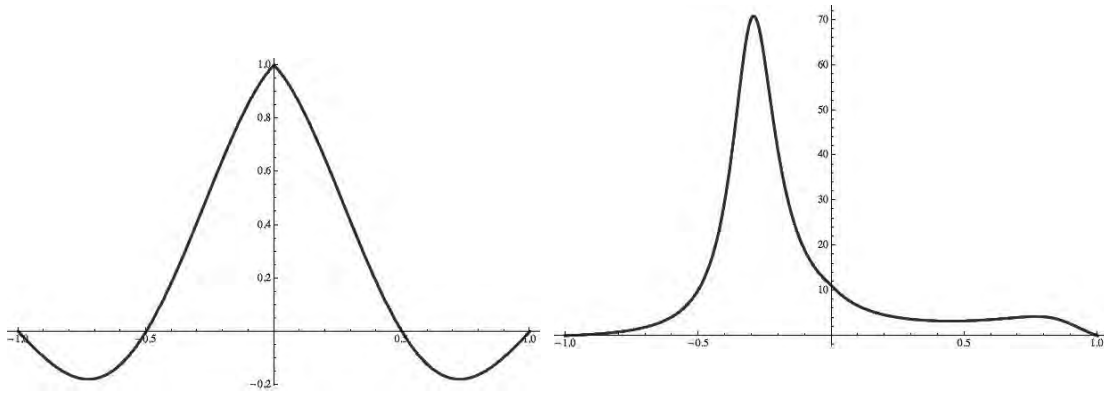


Figure 4.1. Graphics of function $x \rightarrow B_1(x)f_1(x)$ (left) and $x \rightarrow B_1(x)f_2(x)$ (right)

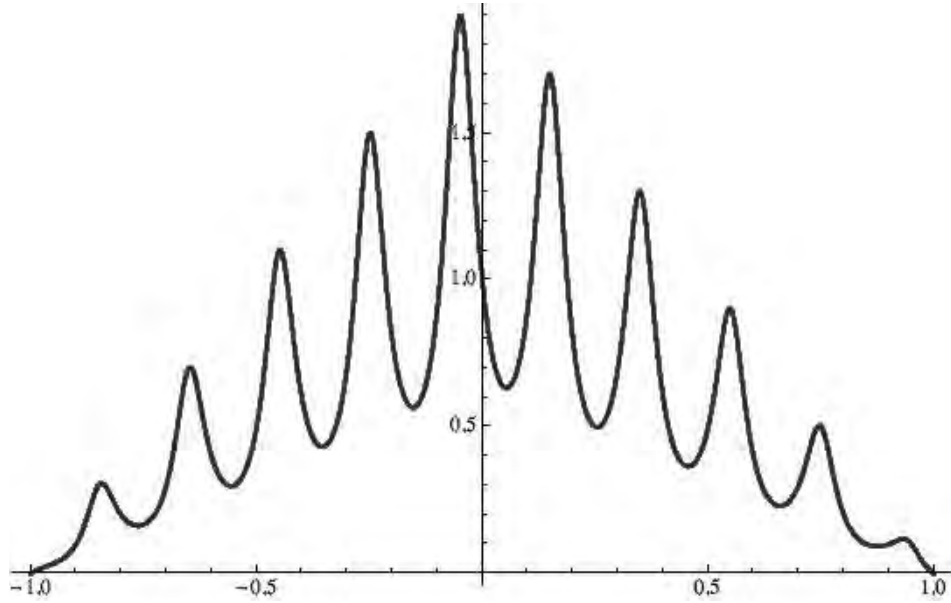


Figure 4.2. Graphics of the function $x \rightarrow B_1(x)f_3(x)$

In Table 4.1 we give the relative error in Gaussian approximations

$$REL_k(n) = \left| \frac{Q_n(f_k) - I_k}{I_k} \right|, k = 1, 2, 3.$$

Numbers in parentheses indicate decimal exponents.

Table 4.1. Relative errors $REL_k(n)$ in Gaussian approximations $Q_n(f_k)$ for $k=1,2,3$

n	$REL_1(n)$	$REL_2(n)$	$REL_3(n)$
5	2.89(-5)	3.33(-1)	1.39(-2)
10	4.01(-15)	1.25(-1)	2.97(-2)
20	1.01(-40)	1.81(-2)	7.79(-2)
30		2.50(-3)	1.39(-2)
40		3.26(-4)	3.69(-4)
50		4.05(-5)	3.32(-4)
100		4.22(-10)	2.68(-6)
150		2.28(-14)	1.05(-6)
200		9.20(-19)	3.63(-9)
250		4.38(-24)	3.79(-10)
300		6.49(-28)	1.49(-12)
350		1.99(-32)	1.81(-14)
400		3.40(-38)	7.64(-16)

As we can see in the case of a smooth function f_1 the convergence is very fast. The relative error is about 10^{-40} for $n=20$ points. As we expected the convergence in the last case is very slow. We must use 400 points in the quadrature rule in order to obtain the so-called double precision result (with about 16 decimal digits).

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